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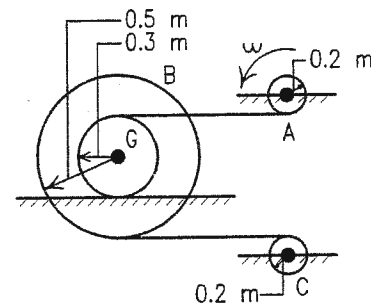
Jan. 30, 2012

**2.5 hours open book Exam.**

- Solve in sequence on the answer booklet.
- The question sheet is not considered in grading.
- Write clearly. Clarity is important in grading.
- Vectors are indicated in bold.
- Take  $g=9.81 \text{ m/s}^2$  or  $g=32.2 \text{ ft/s}^2$ .

No.1– (20%)

The cable from drum A turns the double wheel B, which rolls on its hubs without slipping. At the shown instant, the angular velocity and the angular acceleration of A are respectively  $4 \text{ rad/s}$  and  $3 \text{ rad/s}^2$  respectively, both in the counterclockwise direction. Note that the centers of pulleys A and C are fixed.

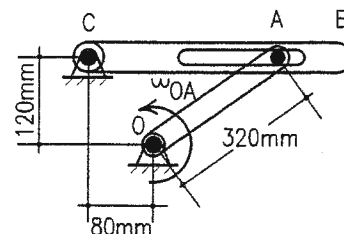


- 5% 1- Determine the angular velocity of the double wheel B at the instant shown.
- 5% 2- Determine the angular velocity of the drum C at the instant shown.
- 10% 3- Determine the angular acceleration of the double wheel B at the instant shown.

No.2– (20%)

Link OA has an angular velocity of  $8 \text{ rad/s}$  as it passes the position shown.

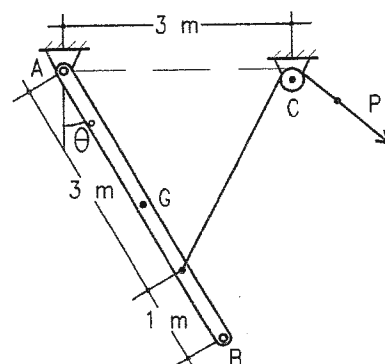
- 10% 1- Determine the angular velocity of link CB.
- 10% 2- Determine the Coriolis component of acceleration of pin A.



No.3– (20%)

The uniform  $100 \text{ kg}$  beam is freely hinged about its upper end A and is initially at rest in the vertical position with  $\theta=0^\circ$ . A force of  $300 \text{ N}$  is applied on the attached cable as shown.

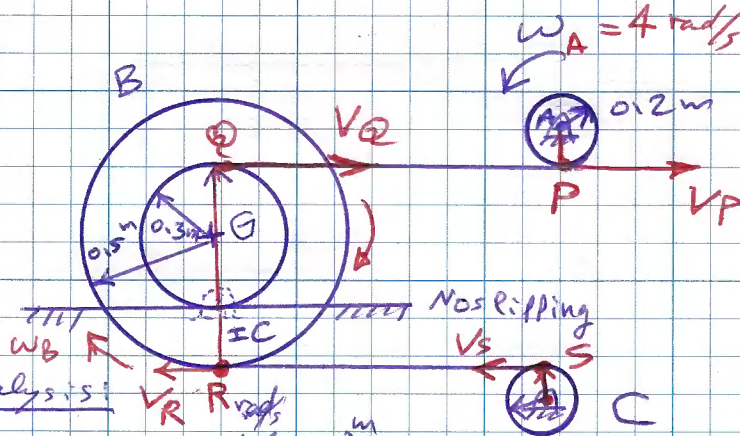
- 5% 1- Draw the free body diagram and the kinetic diagram at the instant  $\theta=0^\circ$ .



Problem 1: No slipping

Given:  $\omega_A = 4 \text{ rad/s}$  ↻  
 $\alpha_A = 3 \text{ rad/s}^2$  ↻

Find  $\omega_B, \omega_C, \alpha_B, \alpha_C$



Velocity Analysis:

1.  $V_P = \omega_A r_A = 4(0.12) = 0.48 \text{ m/s}$   
 $V_P = V_Q = 0.48 \text{ m/s}$  (since A is fixed to B)

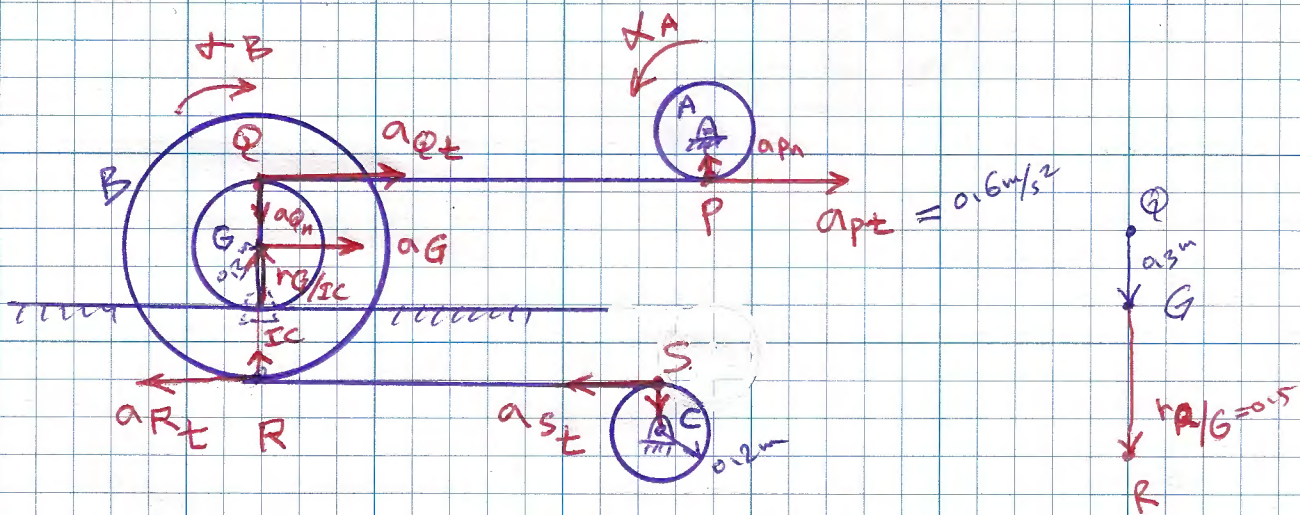
$V_Q = \omega_B r_{Q/IC} = 1.33 \text{ rad/s}$  [on double wheel B]

$\omega_B = \frac{V_Q}{r_{Q/IC}} = \frac{0.48 \text{ m/s}}{0.3 \text{ m}} = 1.33 \text{ rad/s}$  Ans.

2.  $V_R = \omega_B r_{R/IC} = 1.33(0.12) = 0.16 \text{ m/s}$

$V_S = V_R = 0.16 \text{ m/s}$ ;  $V_S = \omega_C r_{S/C}$ ;  $\omega_C = \frac{V_S}{r_{S/C}} = \frac{0.16}{0.12} = 1.33 \text{ rad/s}$  Ans.

3.



3. Pulley A:  $a_{PT} = \alpha_A r_{P/A} = 3 (0.2) = 0.6 \text{ m/s}^2 \rightarrow$

$$a_{PT} = a_{QT} = 0.6 \text{ m/s}^2 \rightarrow ; a_G = \alpha_B r_{G/IC} = 0.3 \alpha_B$$

$$a_G = 0.3 \alpha_B$$

Consider Double wheel B:

$$\vec{a}_G = \vec{a}_Q + \vec{\alpha}_B \times \vec{r}_{G/Q} - \omega_B^2 \vec{r}_{G/Q}$$

$$0.3 \alpha_B \hat{i} = 0.6 \hat{i} - a_{QT} \hat{j} - \alpha_B \hat{k} \times (-0.3 \hat{j}) - (1.33)^2 (-0.3 \hat{j})$$

$$a_G \hat{i} = 0.6 \hat{i} - a_{QT} \hat{j} - 0.3 \alpha_B \hat{i} + 0.533 \hat{j}$$

$$\hat{i}: a_G = 0.6 - 0.3 \alpha_B$$

$$0.3 \alpha_B = 0.6 - 0.3 \alpha_B ; 0.3 \alpha_B + 0.3 \alpha_B = 0.6$$

$$0.6 \alpha_B = 0.6 ; \alpha_B = 1 \text{ rad/s}^2 \text{ Ans.} ; a_G = 0.3 (1) = 0.3 \text{ m/s}^2 \rightarrow$$

to  $\vec{a}_R = \vec{a}_G + \vec{\alpha}_B \times \vec{r}_{R/G} - \omega_B^2 \vec{r}_{R/G}$

$$-a_{RT} \hat{i} + a_{RN} \hat{j} = 0.3 \hat{i} - \hat{k} \times (-0.5 \hat{j}) - (1.33)^2 (-0.5 \hat{j})$$

$$= 0.3 \hat{i} - 0.5 \hat{i} + 0.88445 \hat{j}$$

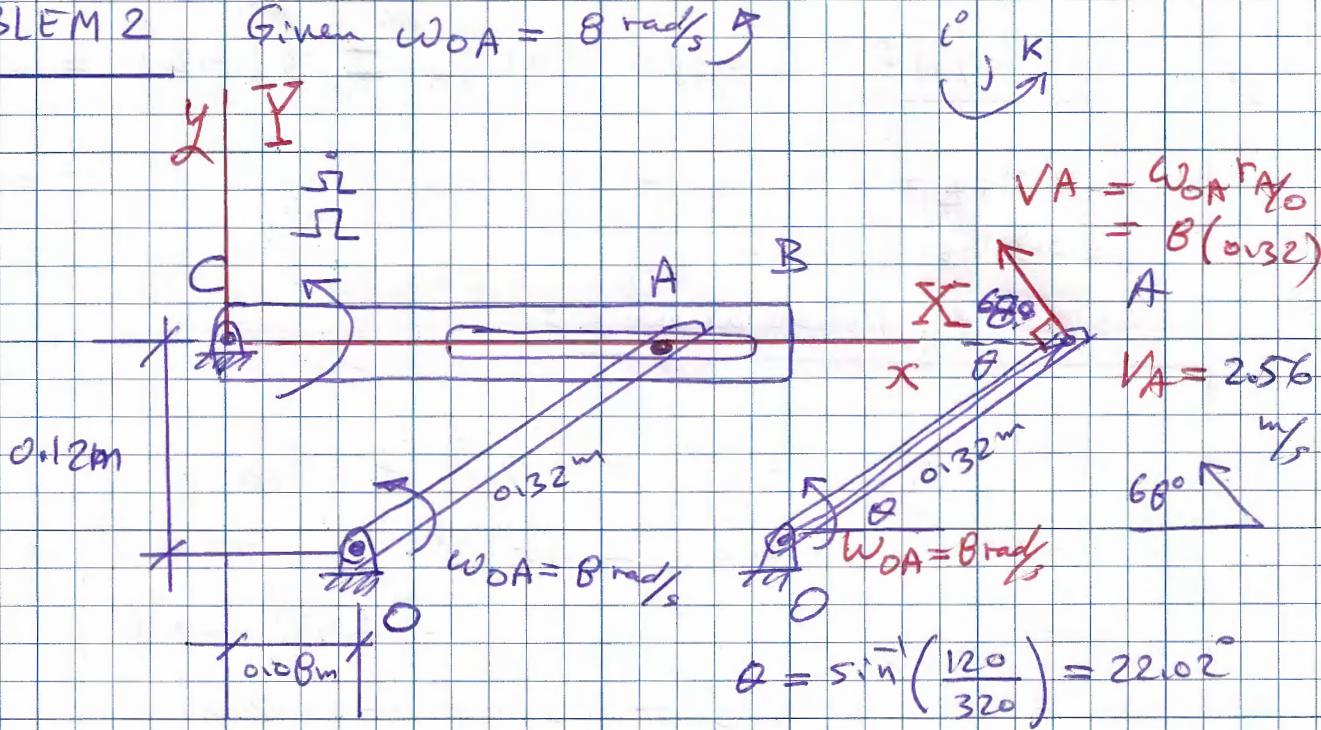
$$\hat{i}: -a_{RT} = 0.3 - 0.5 ; a_{RT} = 0.2 \text{ m/s}^2 \leftarrow$$

$$a_{st} = a_{RT} = 0.2 \text{ m/s}^2$$

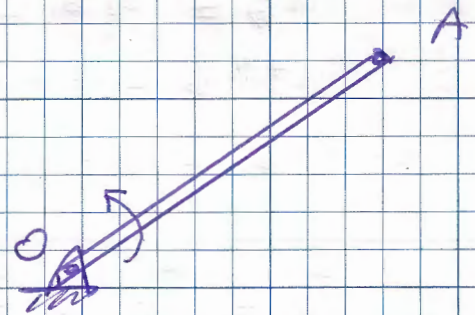
Consider pulley C:  $a_{st} = \alpha_C r_{s/c} ; \alpha_C = \frac{0.2 \text{ m/s}^2}{0.2 \text{ m}} = 1 \text{ rad/s}^2$

$$\alpha_C = 1 \text{ rad/s}^2 \text{ Ans.}$$

PROBLEM 2 Given  $\omega_{OA} = 8 \text{ rad/s}$



$$CA = 80 \text{ mm} + 320 \cos 22.02^\circ = 376.657 \text{ mm}$$



Motion of rotating axes:

$$\begin{aligned} \vec{V}_C &= \vec{0} \text{ Fixed} \\ \vec{a}_C &= \vec{0} \text{ Fixed} \\ \vec{\omega} &= \omega_{CB} \hat{k} \\ \dot{\vec{\omega}} &= \end{aligned}$$

Motion of A w.r.t rotating axes

$$\begin{aligned} r_{A/C} &= 0.376657 \hat{c} \text{ m} \\ (\vec{V}_{A/C})_{XYZ} &= (V_{A/C})_{XY} \hat{c} \\ (\vec{a}_{A/C})_{XYZ} &= \end{aligned}$$

$$\begin{aligned} \vec{V}_A &= \vec{V}_C + \vec{\omega} \times r_{A/C} + (\vec{V}_{A/C})_{XYZ} \\ -2.56 \cos 68^\circ \hat{c} + 2.56 \sin 68^\circ \hat{j} &= \vec{0} + \omega_{CB} \hat{k} \times 0.376657 \hat{c} \\ &= 0.376657 \omega_{CB} \hat{j} + (V_{A/C})_{XY} \hat{c} + (V_{A/C})_{YZ} \hat{c} \end{aligned}$$

$$\hat{j}: 2.56 \sin 68^\circ = 0.376657 \omega_{CB}$$

$$\hat{i}: \omega_{CB} = 6.3017 \text{ rad/s} \text{ Ans.}$$

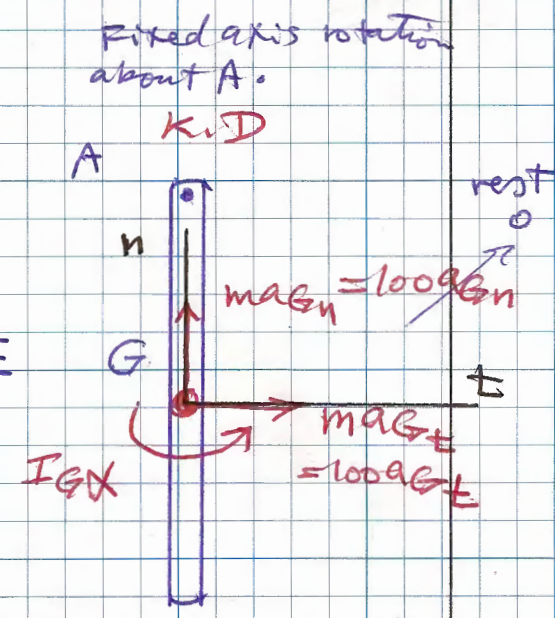
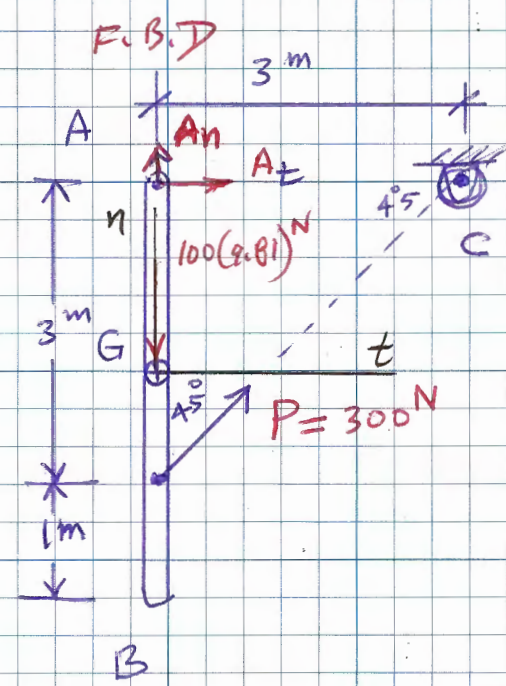
$$2 \vec{\omega} \times \vec{V}_{A/C} = 2(6.3017 \hat{k}) \times -0.959 \hat{c} = -12.087 \hat{j}$$

Problem 3:

Given  $m = 100 \text{ kg}$

@  $\theta = 0^\circ$

1. Draw F.B.D & K.D



2.  $\sum M_A = I_A \alpha$ ; A is a Fixed axis of rotation

$$300 \sin 45^\circ (3) = \left[ \frac{1}{3} (100) 4^2 \right] \alpha_{AB}$$

$$636.396 = 533.3 \alpha_{AB}$$

$$\alpha_{AB} = 1.1932 \text{ rad/s}^2 \text{ } \uparrow \text{ Ans.}$$

$$\alpha_{GE} = \alpha_{AB} \frac{r_{GA}}{r_{AA}}$$

$$\alpha_{GE} = 2 \alpha_{AB} = 2(1.1932)$$

$$I_A = \frac{1}{3} m l^2$$

$$= \frac{1}{3} (100) 4^2$$

$$= 533.3 \text{ kg m}^2$$

3.  $\sum F_n = m a_{gn}$ ;  $300 \cos 45^\circ - 981 \text{ N} + A_n = 0$ ;  $A_n = 768.868 \text{ N} \uparrow$

$\sum F_t = m a_{gt}$ ;  $300 \sin 45^\circ + A_t = 100(2)(1.1932)$

$$A_t = 26.508 \text{ N} \rightarrow ; A = 769.325 \text{ N} ; \alpha = 88^\circ \text{ } \uparrow \text{ Ans.}$$

4. Find  $\omega_{AB}$  @  $\theta = 15^\circ$

$$T_1 + \sum U_{1-2} = T_2 ; T_1 = 0 \text{ rest}$$

$$T_2 = \frac{1}{2} I_A \omega^2 ; A \text{ is Fixed axis}$$

$$= \frac{1}{2} \left[ \frac{1}{3} (100) (4^2) \right] \omega_{AB}^2$$

$$T_2 = 266.67 \omega_{AB}^2$$

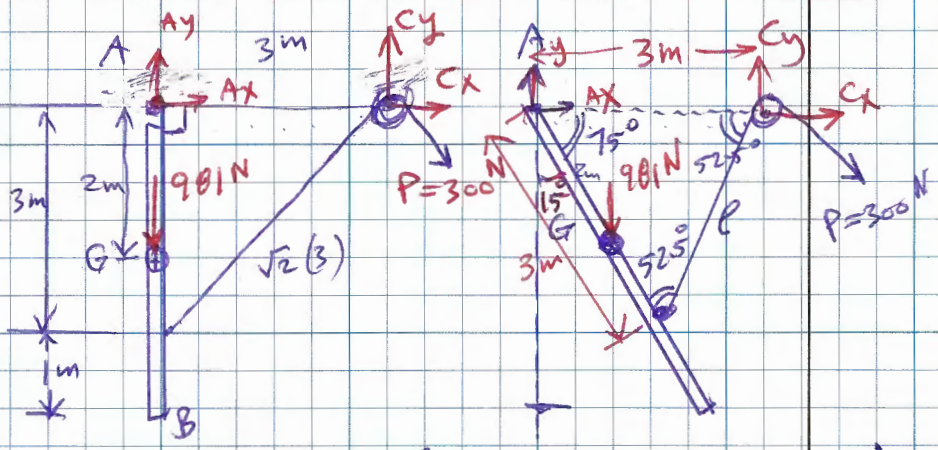
$$\sum U_{1-2} = -981 \text{ N} (2 - 2 \cos 15^\circ)$$

$$+ 300 \text{ N} (\sqrt{2}(3) - 3.6526)$$

$$= -66.8535 + 177.012 = 110.159 \text{ J}$$

substitute:  $0 + 110.159 \text{ J} = 266.67 \omega_{AB}^2$

$$\omega_{AB} = 0.6427 \text{ rad/s} \text{ } \uparrow \text{ Ans.}$$



$$\frac{l}{\sin 75^\circ} = \frac{3}{\sin 52.5^\circ}$$

$$l = 3.6526 \text{ m}$$



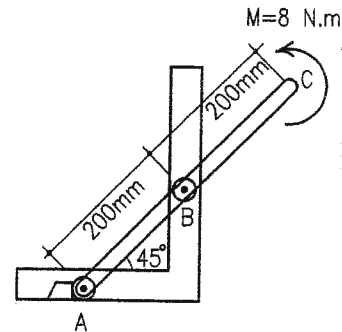
5% 2- Determine the initial angular acceleration of the beam at the instant  $\theta=0^\circ$ .

5% 3- Determine the horizontal and vertical components of the reactions at pin A at the instant  $\theta=0^\circ$ .

5% 4- Determine the angular velocity of the beam when  $\theta=15^\circ$ .

No.4– (20%)

The uniform 3 kg bar ABC is initially at rest with end A bearing against the stop in the horizontal guide. When a constant couple  $M=8 \text{ N.m}$  is applied to end C, the bar rotates causing the end A to strike the side of the vertical guide with a velocity of 3 m/s. There is energy loss due to friction in the guide and the roller.

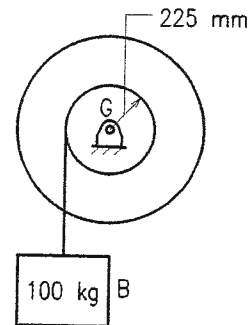


10% 1- Determine the angular velocity of the bar when it is in the vertical position .

10% 2- Determine the energy loss due to friction.

No.5– (20%)

The 320 kg flywheel of a small hoisting engine has a centroidal radius of gyration of 600 mm. The power is cut off when the angular velocity of the flywheel is 100 rpm clockwise. Block B has mass of 100 kg.



10% 1- Draw the impulse and momentum diagrams of the system.

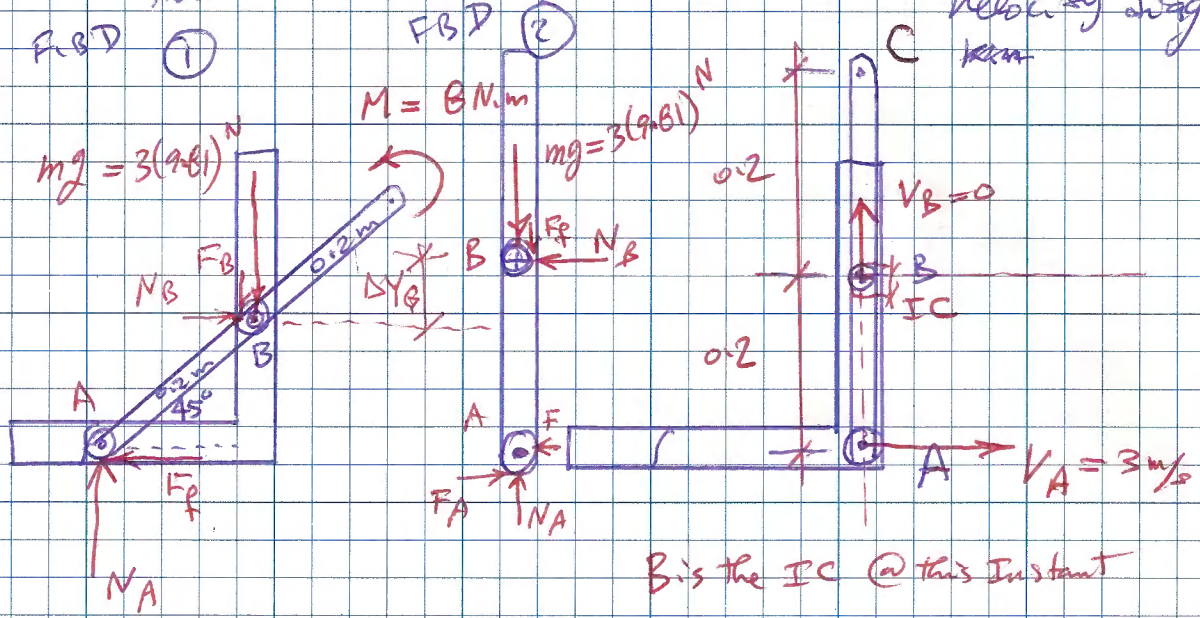
5% 2- Determine the time required for the system to come to rest.

5% 3- Determine the tension in the cord C.

PROBLEM 4:

Given  
 $m_{ABC} = 3 \text{ kg}$   
 (1) @ rest  
 FBD (2)

Abs. velocity by using  
 IC



1

$$I_G = \frac{1}{12} m l^2 = \frac{1}{12} (3) (0.4)^2 = 0.04 \text{ kg}\cdot\text{m}^2$$

B is the IC @ this instant  
 $\Rightarrow V_A = \omega_{ABC} r_{A/IC}$   
 $\omega_{ABC} = \frac{V_A}{r_{A/IC}} = \frac{3}{0.2} = 15 \text{ rad/s}$  Ans.

2-  $T_1 + \Sigma U_{1-2} = T_2$

$T_1 = 0$  rest;  $T_2 = \frac{1}{2} I_{IC} \omega_{ABC}^2 = \frac{1}{2} \left[ \frac{1}{12} m l^2 \right] \omega_{ABC}^2$

$T_2 = \frac{1}{2} \left[ \frac{1}{12} 3^{kg} 0.4^2 \right] (15^2) = 4.5 \text{ J}$

$\Sigma U_{1-2} = mg \Delta Y_G + M \Delta \theta + U_{1-2 \text{ friction}}$

$\Delta Y_G = 0.2 - 0.2 \sin 45^\circ = 0.2(1 - \sin 45^\circ) \text{ m}$  ↑

$\Delta \theta = \frac{\pi}{4}$

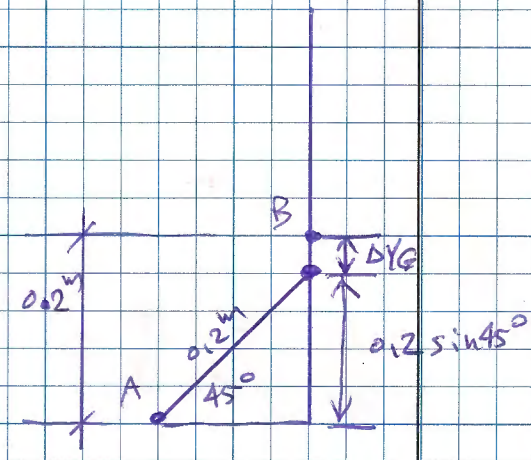
$\therefore \Sigma U_{1-2} = -0.2(1 - \sin 45^\circ) 3(9.81) + 8^{Nm} \left( \frac{\pi}{4} \right) + U_{1-2 \text{ friction}}$

$= -1.72397 \text{ J} + 6.2832 \text{ J} + U_{1-2 \text{ friction}}$

$= 4.5592 + U_{1-2 \text{ friction}}$

substitute:  $0 + 4.5592 \text{ J} + U_{1-2 \text{ friction}} = 4.5 \text{ J}$

$U_{1-2 \text{ friction}} = -0.05922 \text{ J}$  Ans.



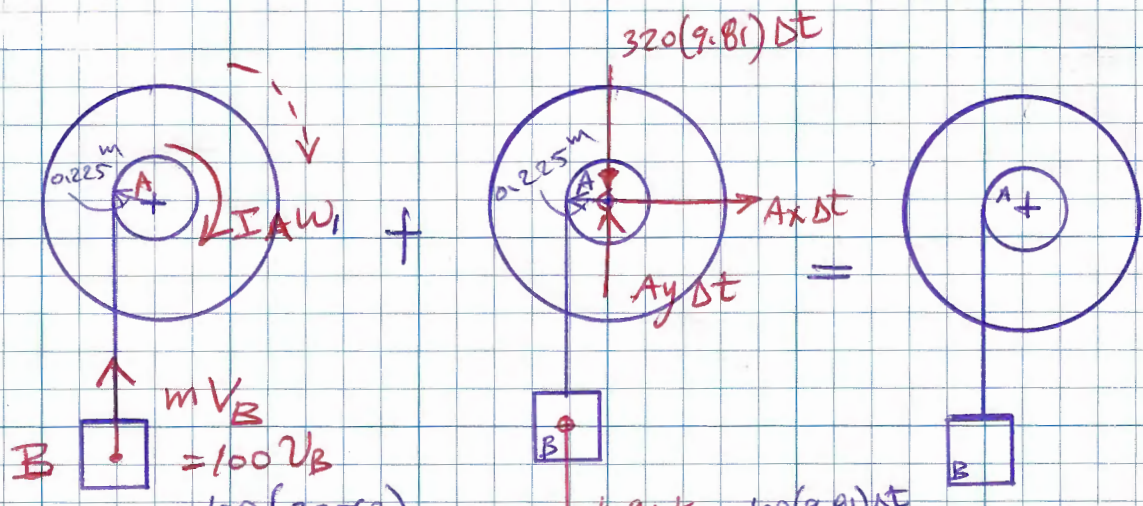
PROBLEMS:  $m_A = 320 \text{ kg}$ ;  $K_G = 600 \text{ mm} = 0.6 \text{ m}$

$$\omega_1 = \frac{100 \text{ rev/min}}{60 \text{ s/min}} \times \frac{2\pi \text{ rad/rev}}{1} = 10.472 \text{ rad/s}$$

$$v_B = \omega r_{B/A} = 10.472 \text{ rad/s} (0.225 \text{ m})$$

$$v_B = 2.3562 \text{ m/s} \uparrow$$

1. Draw I & M diagrams:



Initial M. diagram

Impulse Diagram

Final Momentum Diagram  
(system came to a stop)

$$I_A = m_A K_A^2 = 320(0.6)^2 = 115.2 \text{ kg}\cdot\text{m}^2$$

2. Find  $\Delta t$

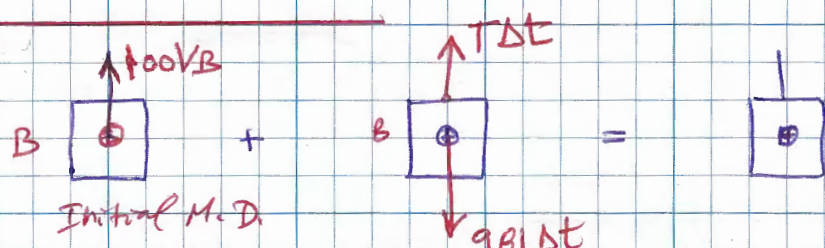
$$\sum (\text{moments})_A = 0$$

$$I_A \omega_1 + 100 v_B (0.225) \oplus - 100(9.81) \Delta t (0.225) = 0$$

$$115.2 \text{ kg}\cdot\text{m}^2 \times (10.472 \text{ rad/s}) + 100(2.3562)(0.225) = 981(0.225) \Delta t$$

$$\Delta t = 5.7057 \text{ s Ans.}$$

3. Consider only Block B:



Final M. Diagram

$$\sum (\text{vectors})_y = 0$$

$$100(2.3562) + T(5.7057) - 981(5.7057) = 0$$

$$T = 939.704 \text{ N Ans.}$$